## **Module 4: z transform**

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Introduction

Definition

Zeros and Poles

Region of Convergence

# The z-Transform Introduction

## Why z-Transform?

- A generalization of Fourier transform
- Why generalize it?
  - FT does not converge on all sequence
  - Notation good for analysis
  - Bring the power of complex variable theory deal with the discrete-time signals and systems

# Definition

• The *z*-transform of sequence *x*(*n*) is defined by

$$X(z) = \sum_{n=-\infty}^{\infty} x(n) z^{-n}$$

• Let  $z = e^{-j\omega}$ .

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x(n)e^{-j\omega n}$$



Fourier Transform is to evaluate ztransform on a unit circle.

# z-Plane



#### **Periodic Property of FT**



## The z-Transform Zeros and Poles

## Definition

 Give a sequence, the set of values of z for which the ztransform converges, i.e., |X(z)|<∞, is called the region of convergence.

$$|X(z)| = \left|\sum_{n=-\infty}^{\infty} x(n) z^{-n}\right| = \sum_{n=-\infty}^{\infty} |x(n)|| z|^{-n} < \infty$$

ROC is centered on origin and consists of a set of rings.

#### **Example: Region of Convergence**

$$|X(z)| = \left| \sum_{n = -\infty}^{\infty} x(n) z^{-n} \right| = \sum_{n = -\infty}^{\infty} |x(n)|| |z|^{-n} < \infty$$



### **Stable Systems**

• A stable system requires that its Fourier transform is uniformly convergent.



- Fact: Fourier transform is to evaluate *z*-transform on a unit circle.
- A stable system requires the ROC of *z*-transform to include the unit circle.

#### Example: A right sided Sequence

$$x(n) = a^n u(n)$$



#### **Example: A right sided Sequence**

$$x(n) = a^n u(n)$$

$$X(z) = \sum_{n=-\infty}^{\infty} a^n u(n) z^{-n}$$

$$=\sum_{n=0}^{\infty}a^{n}z^{-n}$$
$$=\sum_{n=0}^{\infty}(az^{-1})^{n}$$

For convergence of X(z), we require that

$$\sum_{n=0}^{\infty} |az^{-1}| < \infty \implies |az^{-1}| < 1$$

$$X(z) = \sum_{n=0}^{\infty} (az^{-1})^n = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$

|z| > |a|

## Example: A right sided Sequence ROC for $x(n)=a^nu(n)$

$$X(z) = \frac{z}{z-a}, \qquad |z| > |a|$$

### Which one is stable





### **Example: A left sided Sequence**

$$x(n) = -a^n u(-n-1)$$



#### Example: A left sided Sequence

$$x(n) = -a^n u(-n-1)$$

$$X(z) = -\sum_{n=-\infty}^{\infty} a^n u(-n-1) z^{-n}$$

$$=-\sum_{n=-\infty}^{-1}a^nz^{-n}$$

$$= -\sum_{n=1}^{\infty} a^{-n} z^n$$

$$=1-\sum_{n=0}^{\infty}a^{-n}z^{n}$$

For convergence of X(z), we require that

$$\sum_{n=0}^{\infty} |a^{-1}z| < \infty \implies |a^{-1}z| < 1$$

$$X(z) = 1 - \sum_{n=0}^{\infty} (a^{-1}z)^n = 1 - \frac{1}{1 - a^{-1}z} = \frac{z}{z - a}$$

|z| < |a|

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## Example: A left sided Sequence ROC for $x(n) = -a^n u(-n-1)$

$$X(z) = \frac{z}{z-a}, \qquad |z| < |a|$$

#### Which one is stable





## **The z-Transform** Region of Convergence

# Represent z-transform as a Rational Function

$$X(z) = \frac{P(z)}{Q(z)}$$

where P(z) and Q(z) are polynomials in *z*.

#### Zeros: The values of *z*'s such that X(z) = 0Poles: The values of *z*'s such that $X(z) = \infty$

#### **Example: A right sided Sequence**

$$x(n) = a^n u(n)$$
  $X(z) = \frac{z}{z-a}, \quad |z| > |a|$ 



ROC is bounded by the pole and is the exterior of a circle.

#### **Example: A left sided Sequence**

$$x(n) = -a^n u(-n-1)$$
  $X(z) = \frac{z}{z-a}, \quad |z| < |a|$ 



ROC is bounded by the pole and is the interior of a circle.

Example: Sum of Two Right Sided Sequences



#### **Example: A Two Sided Sequence** $x(n) = (-\frac{1}{3})^n u(n) - (\frac{1}{2})^n u(-n-1)$ $X(z) = \frac{z}{z + \frac{1}{3}} + \frac{z}{z - \frac{1}{2}} = \frac{2z(z - \frac{1}{12})}{(z + \frac{1}{2})(z - \frac{1}{2})}$ lmROC is bounded by poles and is a ring. 1/12 Re -1/3ROC does not include any pole.



## **Properties of ROC**

- A ring or disk in the z-plane centered at the origin.
- The Fourier Transform of *x*(*n*) is converge absolutely iff the ROC includes the unit circle.
- The ROC cannot include any poles
- Finite Duration Sequences: The ROC is the entire *z*-plane except possibly z=0 or  $z=\infty$ .
- Right sided sequences: The ROC extends outward from the outermost finite pole in X(z) to  $z=\infty$ .
- Left sided sequences: The ROC extends inward from the innermost nonzero pole in *X*(*z*) to *z*=0.

Consider the rational *z*-transform with the pole pattern:

Find the possible ROC's



Consider the rational *z*-transform with the pole pattern:

**Case 1: A right sided Sequence.** 



Consider the rational *z*-transform with the pole pattern:

**Case 2: A left sided Sequence.** 



Consider the rational *z*-transform with the pole pattern:

**Case 3: A two sided Sequence.** 



Consider the rational *z*-transform with the pole pattern:

**Case 4: Another two sided Sequence.** 

